# Computer Aided Manufacturing





Dr.S.RAMABALAN,
PRINCIPAL,
E.G.S. PILLAY ENGINEERING COLLEGE,
NAGAPATTINAM.



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## **Unit III**

# PROGRAMMING OF CNC LATHE

Coordinate system - structure of a part program -G & M Codes -Programming for FANUC and SIEMENS controller -Single pass and canned cycle -Turning, facing and threading -Multi-pass canned cycle -Rough and Finish turning, facing, pattern repeating, grooving, threading, drilling, boring, peck drilling, high speed drilling cycle -Subprogram and Macro programming -Tool length and nose radius compensation - offset -Tool, work and coordinate -Insert -Materials, Classification, Nomenclature and Selection -Tool and Work holding devices -Automatic tool changer -Turret and drum type -Tool holder nomenclature and selection -CNC part programming using CAD/CAM software and interfacing with CNC machines

1 February 2023

# Cleansing through Breathing



# Recap and review of previous class

Let's Recap

# Prerequisite Knowledge

- Knowledge on conventional machining
- Fundamentals of metal removal processes

# 3.EVOCATION





1 February 2023

# 4. GENERAL OBJECTIVE (GO)

Students will be able to apply the knowledge to create the CNC part program for circular components in FANUC & SIEMENS controller.

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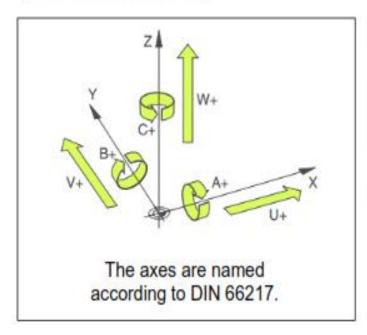
# 5. SPECIFIC OBJECTIVE (SO) MAPPED WITH STEM

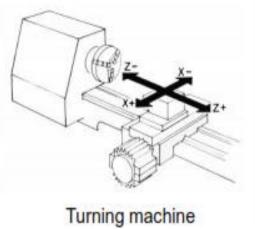
The students will be able to

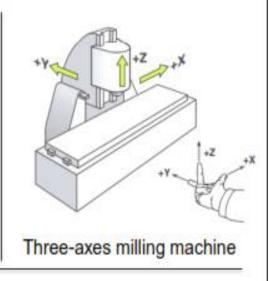
- 1. Recall the coordinate systems used in CNC machines. (R-F) (E)
- 2. Explain the structure of part programming in CNC machines. (U-C) (E)
- 3. Exemplify the canned cycles used in CNC Lathe programming in FANUC and SIEMENS controller. (U-C) (E)
- 4. Construct the part program for given cylindrical component. (Ap-C) (E)

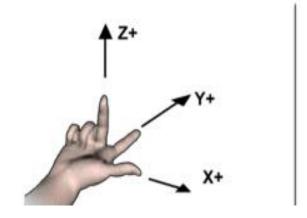
1 February 2023 8

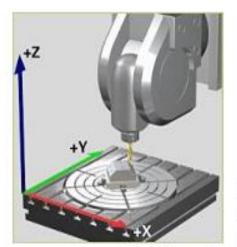
### Axis nomenclature

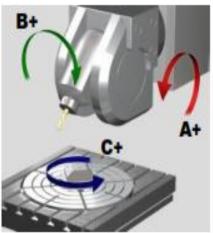






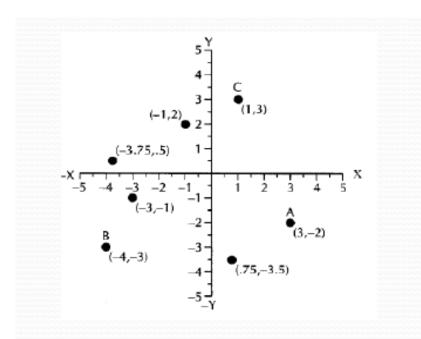


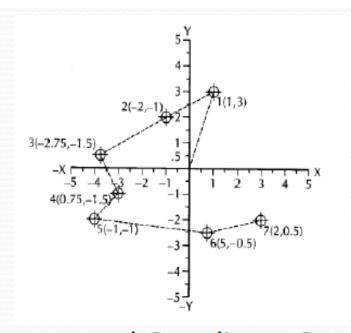




Six-axis milling machine

## Based on Coordinate system





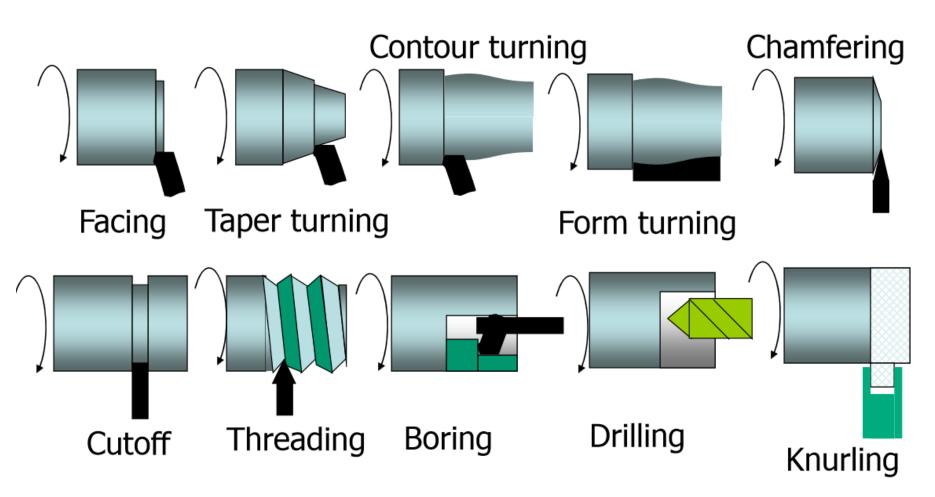
Absolute Coordinate System

Incremental Coordinate System

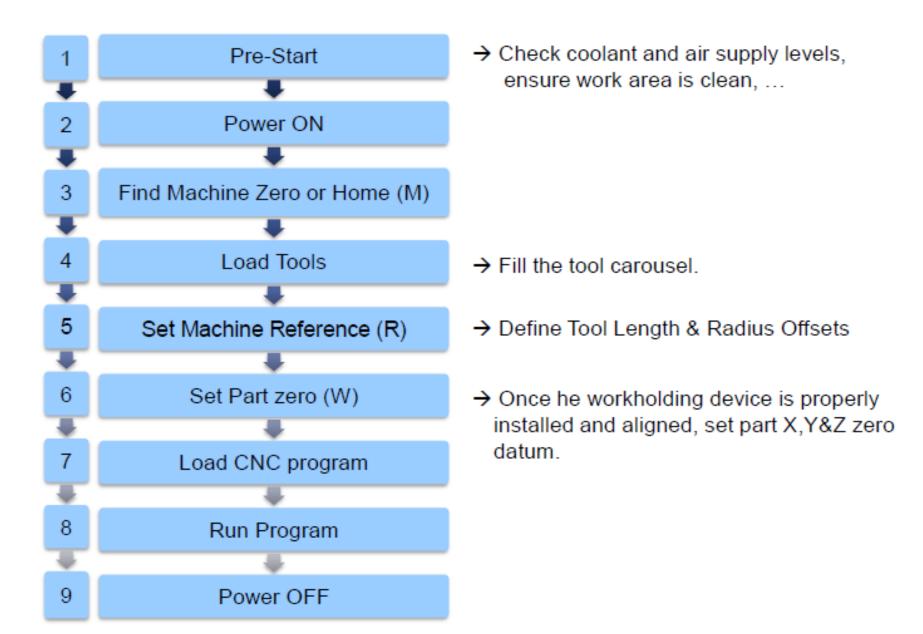
# CNC Programming – Turning



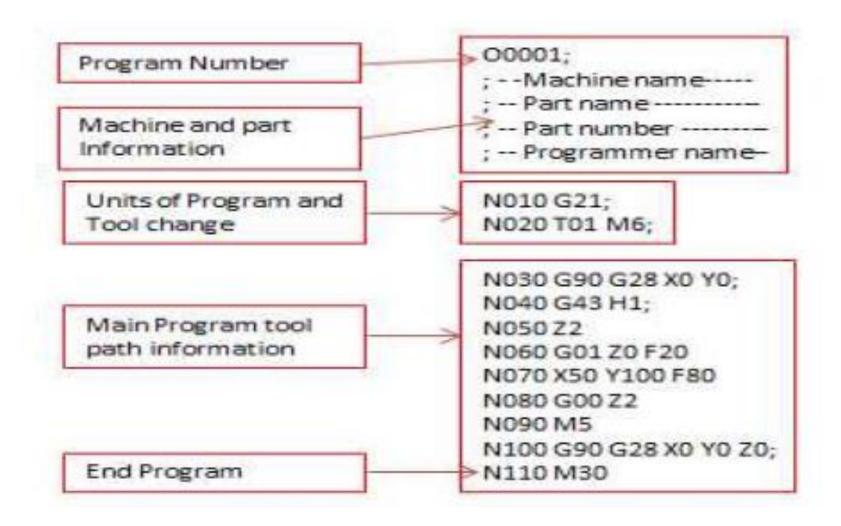
# Sequence of operation



# CNC machine setup and operation



# Structure of a part program

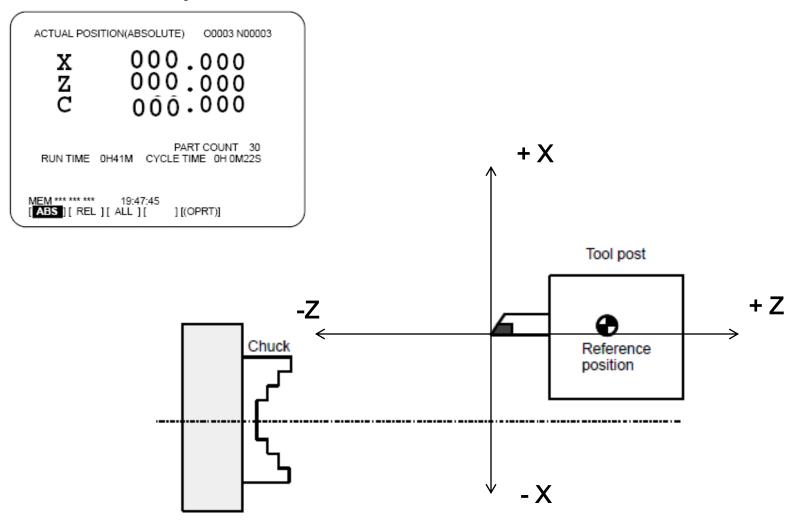


## **Programming Key Letters**

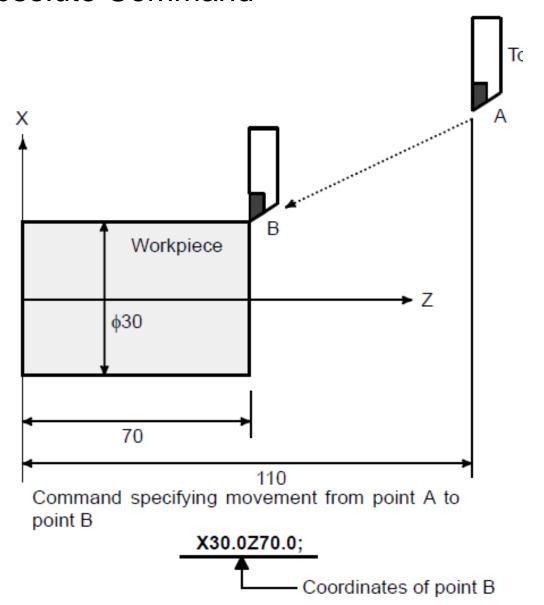
- O Program number (Used for program identification)
- N Sequence number (Used for line identification)
- G Preparatory function or Geometry code
- X X axis designation
- Y Y axis designation
- Z Z axis designation
- R Radius designation
- F Feed rate designation
- S Spindle speed designation
- H Tool length offset designation
- D Tool radius offset designation
- T Tool Designation
- M Miscellaneous function or Machine function

## MACHINE COORDINATE SYSTEM

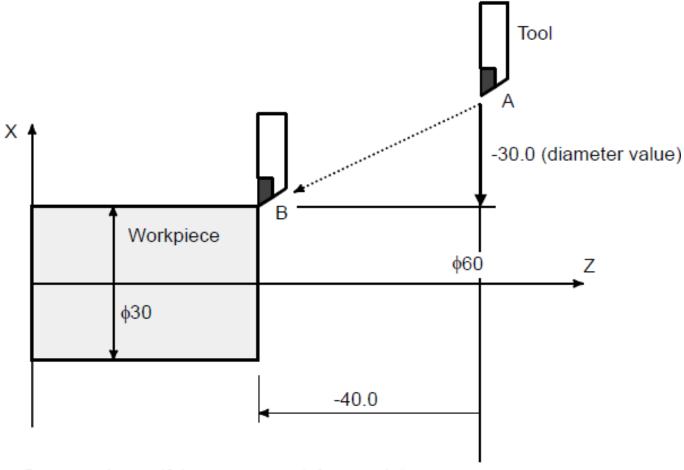
This coordinate system is established in CNC controller after referencing



## **Absolute Command**



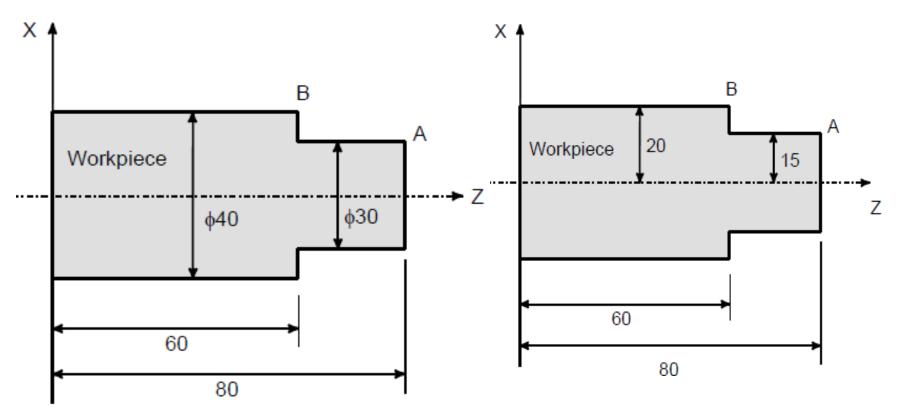
## Incremental command



Command specifying movement from point A to point B

U-30.0 W-40.0

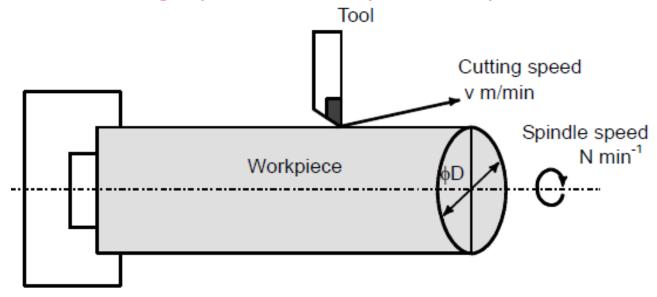
Distance and direction for movement along each axis



Coordinate values of points A and B A(30.0, 80.0), B(40.0, 60.0)

Coordinate values of points A and B A(15.0, 80.0), B(20.0, 60.0)

## **Cutting Speed and Spindle Speed**



Cutting Speed is nothing but linear speed of the tool over the job

Cutting speed depends on tool material and job material

Spindle speed is the number of rotation per minute made by Spindle

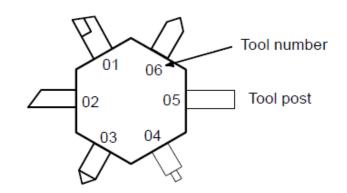
$$N = 1000 * V$$
 N=spindle speed(RPM), V = Cutting Speed ( m/min )  $\pi$  D = Diameter in mm

Ex. Cutting Speed = 30 Met/Min, Job Dia. = 15 mm, Spindle Speed = \_\_\_\_\_

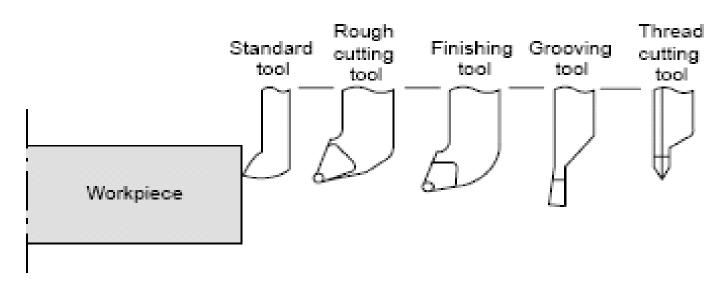
## SELECTION OF TOOL

Tool 2 and offset 2 is referred as **T0202** in the program

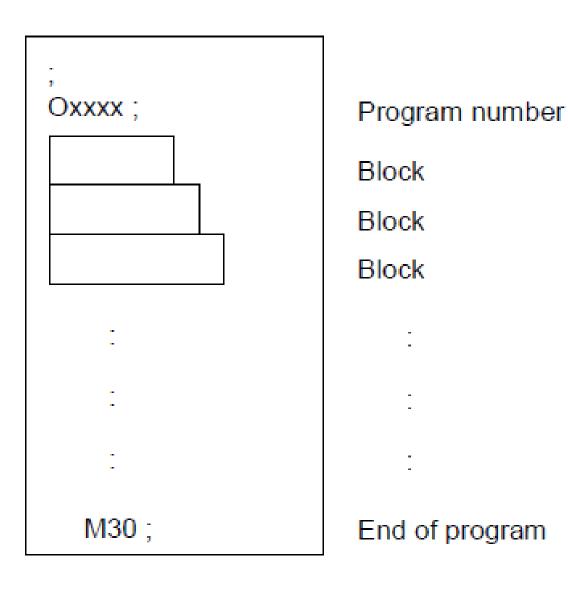
Below are commonly used tools



- Tool offsets are used to compensate for the length variation of different tools

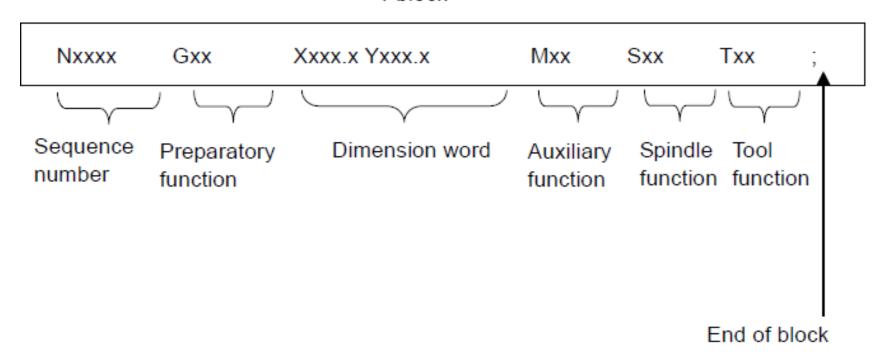


## PROGRAM CONFIGURATION



#### **Block configuration**

1 block



## Program structure continued:

#### Program data

It is possible to set Decimal type entry or Calculator type using CNC parameter(3401#0).

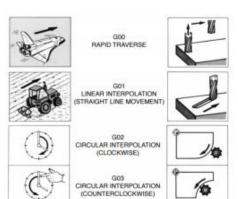
( Usual setting is decimal type data entry )

### Decimal Entry (P3401#0=0)

X40.0 is treated as 40 mm X40 is treated as 40 microns

#### Calculator type entry (P3401#0=1)

X40.0 is treated as 40 mm X40 is also treated as 40 mm



## G – Codes

(	code syste	m	Group	Function
Α	В	С		
G00	G00	G00	01	Positioning (Rapid traverse)
G01	G01	G01		Linear interpolation (Cutting feed)
G02	G02	G02		Circular interpolation CW or helical interpolation CW
G03	G03	G03		Circular interpolation CCW or helical interpolation CCW
G20	G20	G70	06	Input in inch
G21	G21	G71		Input in mm
G27	G27	G27	00	Reference position return check
G28	G28	G28		Return to reference position
G30	G30	G30		2nd, 3rd and 4th reference position return
G31	G31	G31		Skip function
G40	G40	G40		Tool nose radius compensation : cancel
G41	G41	G41	07	Tool nose radius compensation : left
G42	G42	G42		Tool nose radius compensation : right

		L		
G54	G54	G54	14	Workpiece coordinate system 1 selection
G55	G55	G55		Workpiece coordinate system 2 selection
G56	G56	G56		Workpiece coordinate system 3 selection
G57	G57	G57		Workpiece coordinate system 4 selection
G58	G58	G58		Workpiece coordinate system 5 selection
G59	G59	G59		Workpiece coordinate system 6 selection
G70	G70	G72	00	Finishing cycle
G71	G71	G73		Stock removal in turning
G72	G72	G74		Stock removal in facing
G73	G73	G75		Pattern repeating cycle
G74	G74	G76		End face peck drilling cycle
G75	G75	G77		Outer diameter/internal diameter drilling cycle
G76	G76	G78		Multiple-thread cutting cycle
G98	G94	G94	05	Feed per minute
G99	G95	G95		Feed per revolution
-	G90	G90	03	Absolute programming
-	G91	G91		Incremental programming

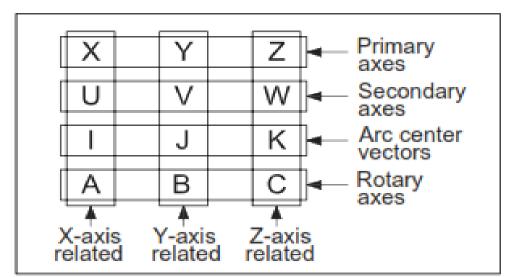
## **Table of Important M codes**

M Codes are instructions describing miscellaneous functions like calling the tool, spindle rotation, coolant on/off etc.,

Program Stop
Optional Stop
Program End
Spindle Forward
Spindle Reverse
Spindle Stop
Automatic Tool change
Coolant On
Coolant Off
Vice / Chuck Open
Vice / Chuck Close
Program Stop & Rewind
Door Open
Door Close
Sub program Call
Subprogram Exit

## Additional Axes

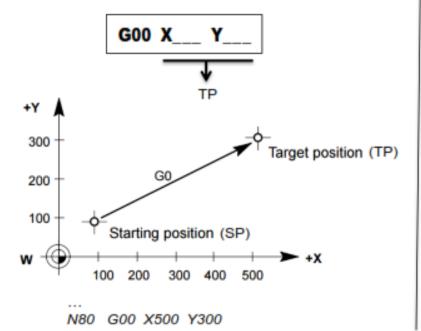
- A CNC machine of any type can be designed with one or more additional axes, normally designated as the secondary or parallel axes using the U, V and W letters.
- For a rotary or an indexing applications, additional axes are defined as A, B and C axes, as being rotated about the X, Y and Z axes, again in their respective order.
- Positive direction of a rotary (or an indexing) axis is the direction required to advance a right handed screw in the positive X, Y or Z axis.



#### Preparatory functions or G-codes

#### Rapid traverse (G00)

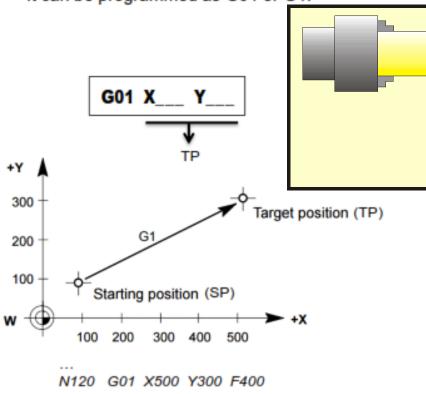
- It is a positioning linear movement at maximum
   F value defined in the machine parameters.
- Not valid for cutting.
- It can be programmed as G00, G0 or G.



#### Linear interpolation (G01)

 It is a working linear movement at the programmed F value.

It can be programmed as G01 or G1.

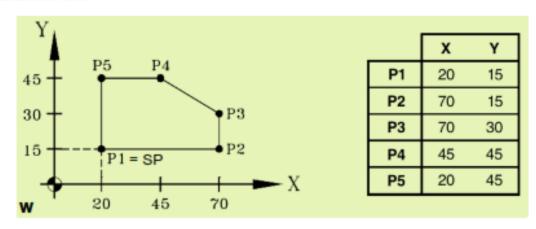


### Preparatory functions or G-codes

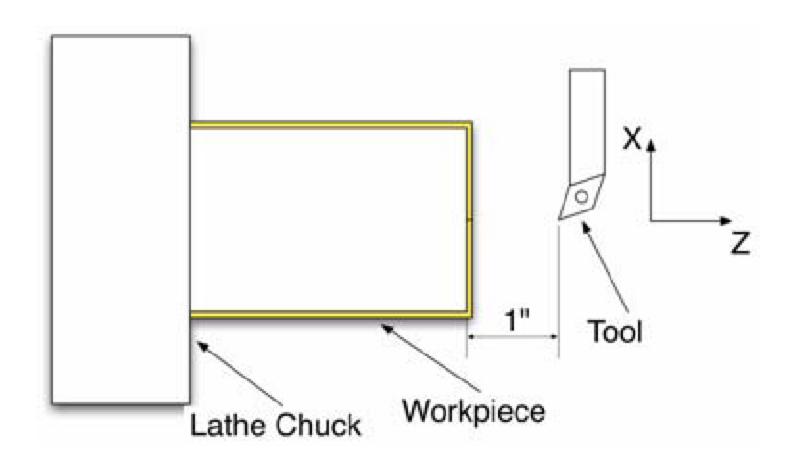
#### Rapid traverse (G00)

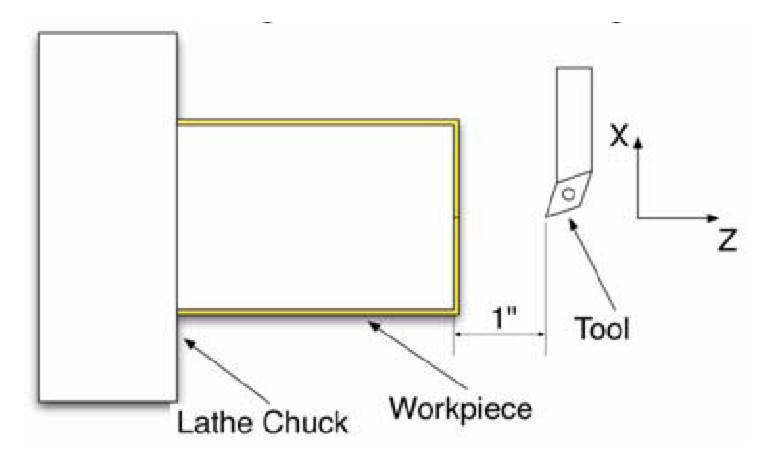
## Linear interpolation (G01)

#### **EXERCISE 1**



# **Lathe Turning**



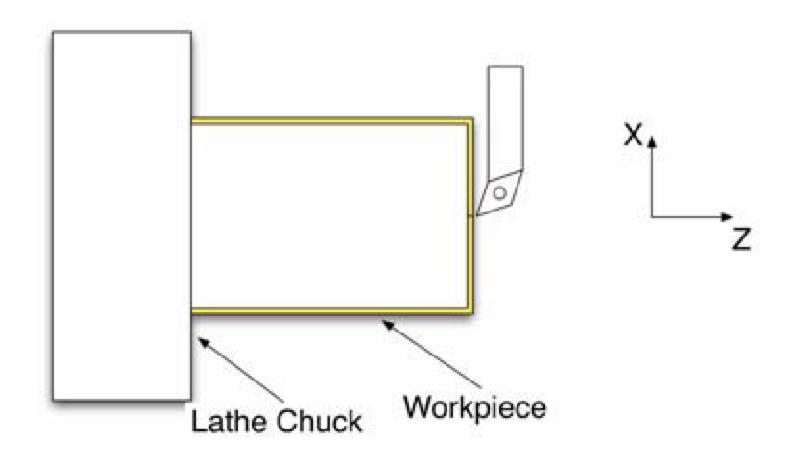


N001 G90 ; Absolute coordinate system

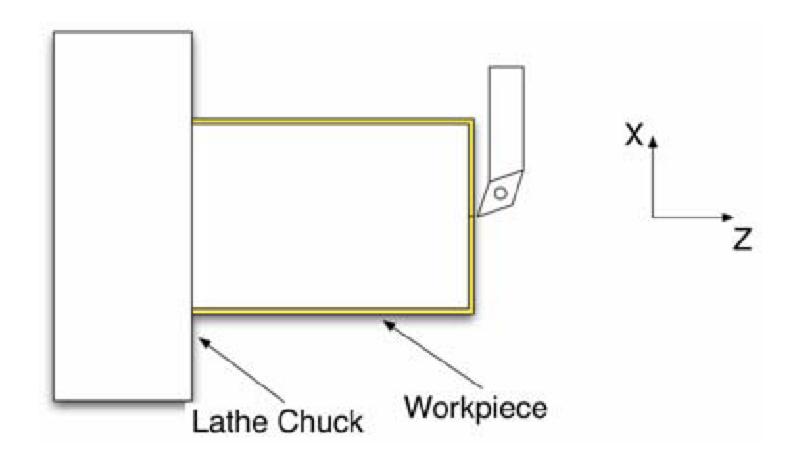
N002 M06 T01 ; Select tool #1 (turning tool)

N003 M03 S2000 ; Turn spindle on (CW), set 2000 rpm

N004 G00 X0.0 Z-0.9 ; Rapid traverse

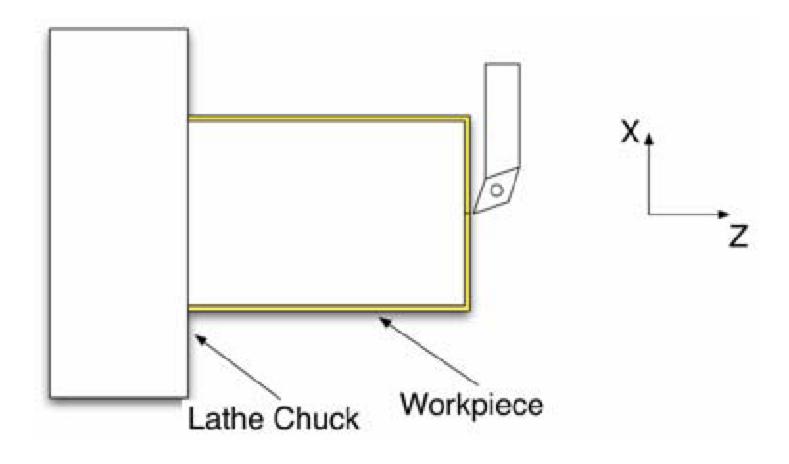


N004 G00 X0.0 Z-0.9 ; Rapid Traverse

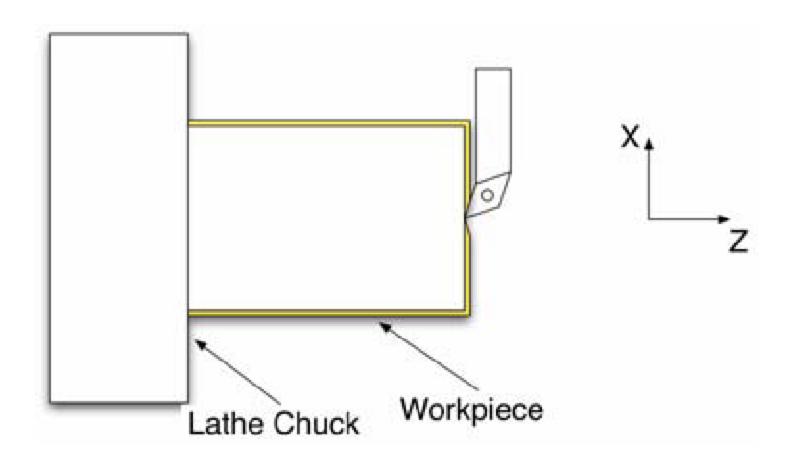


N004 G00 X0.0 Z-0.9 ; Rapid Traverse

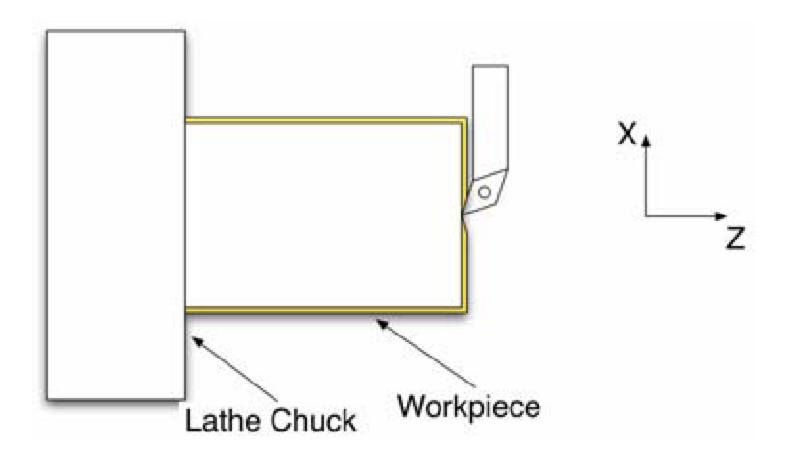
Do not run the tool into the workpiece during Rapid Traverse!



N005 G01 X0.0 Z-1.0 F10 ; enter part

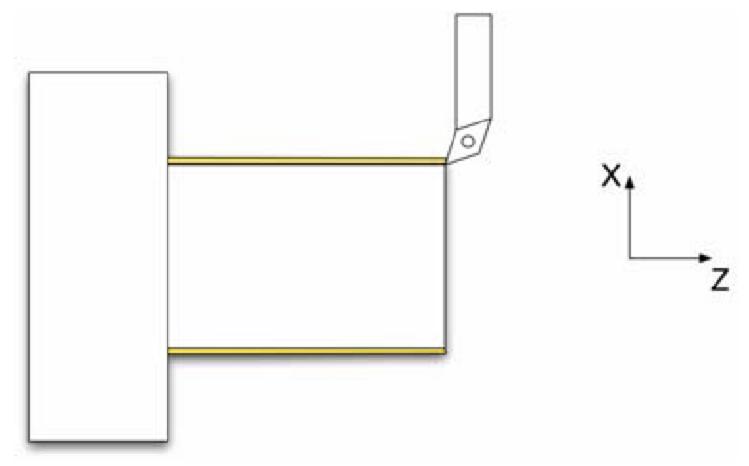


N005 G01 X0.0 Z-1.0 F10 ; enter part



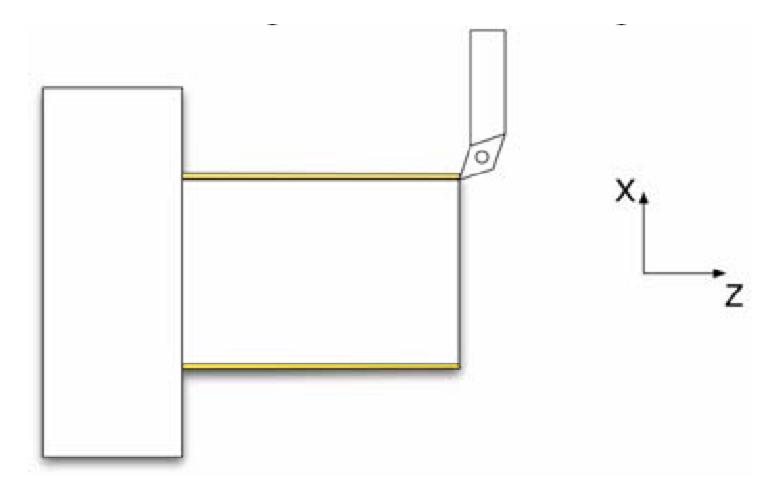
N005 G01 X0.0 Z-1.0 F10 ; enter part

N006 G01 X1.0 Z-1.0 F10 ; make facing cut



N005 G01 X0.0 Z-1.0 F10 ; enter part

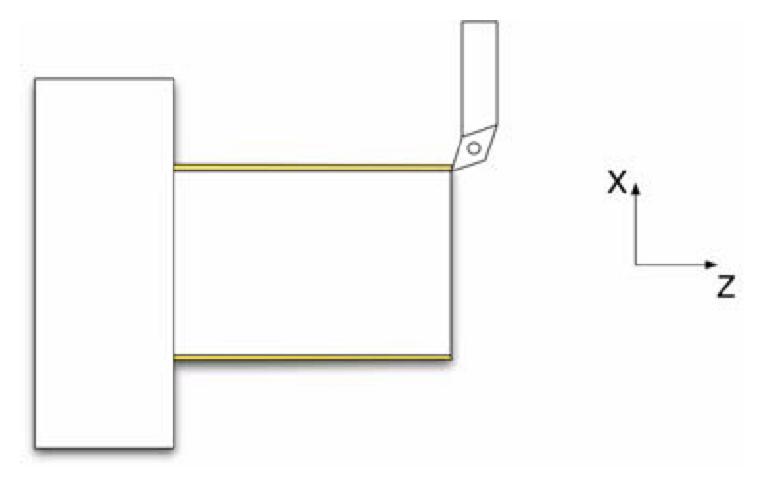
N006 G01 X1.0 Z-1.0 F10 ; make facing cut



N005 G01 X0.0 Z-1.0 F10 ; enter part

N006 G01 X1.0 Z-1.0 F10 ; make facing cut

N006 G01 X1.0 ; can omit unchanged values

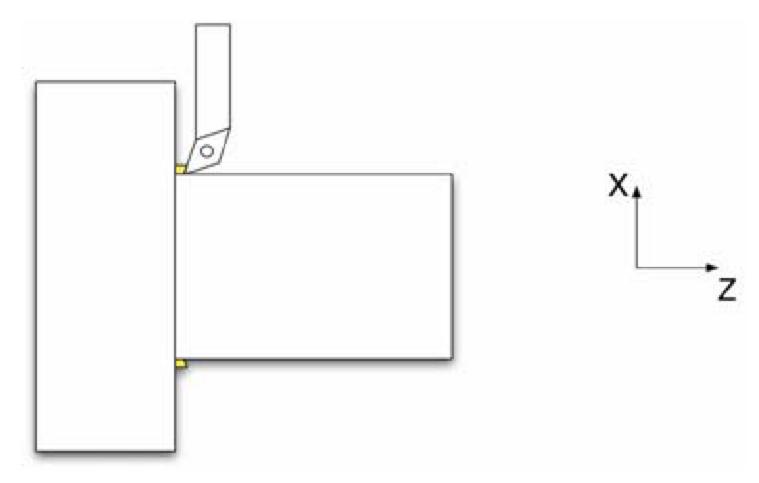


N006 G01 X1.0

N007 G01 Z-3.9

; make facing cut

; turn side

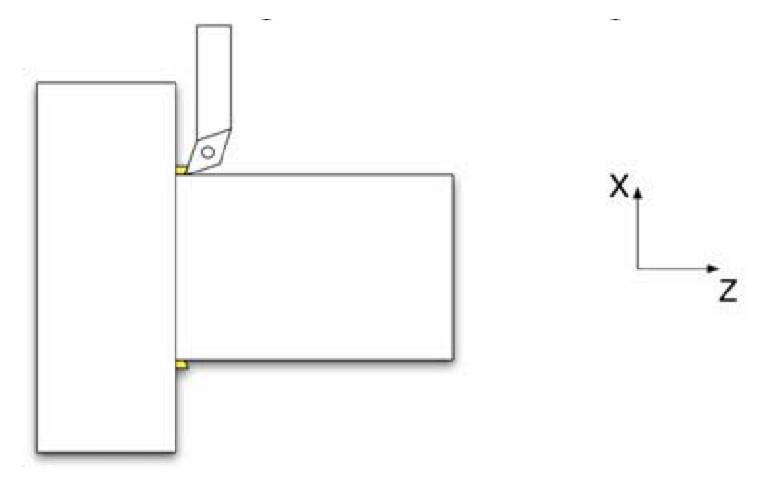


N006 G01 X1.0

N007 G01 Z-3.9

; make facing cut

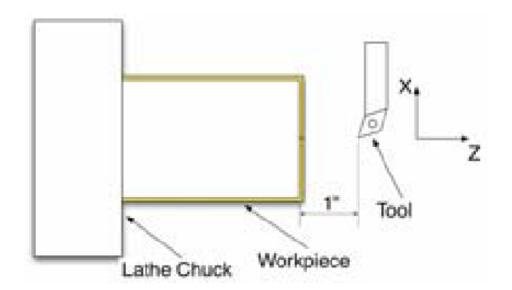
; turn side



N006 G01 X1.0 ; make facing cut

N007 G01 Z-3.9 ; turn side

Do not run the tool into the chuck during machining!



N001 G90 ; Absolute coordinate system

N002 M06 T01 ; Select tool #1 (turning tool)

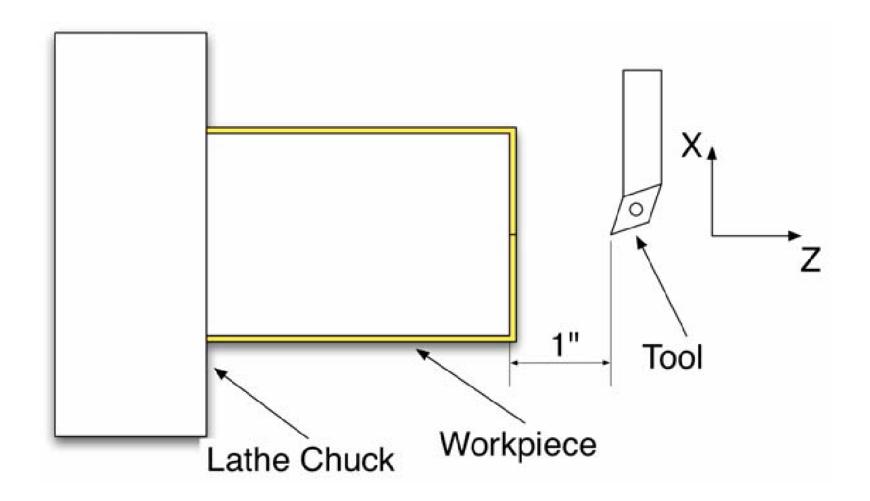
N003 M03 S2000 ; Turn spindle on (CW), set 2000 rpm

N004 G00 X0.0 Z-0.9 ; Rapid traverse

N005 G01 X0.0 Z-1.0 F10 ; enter part

N006 G01 X1.0 ; make facing cut

N007 G01 Z-3.9 ; turn side



N001 G90 ; Absolute coordinate system

N002 M06 T01 ; Select tool #1 (turning tool)

N003 M03 S2000 ; Turn spindle on (CW), set 2000 rpm

N004 G00 X0.0 Z-0.9 ; Rapid traverse

N005 G01 Z-1.0 F10 ; Enter part

N006 X1.0 ; Make facing cut

N007 Z-3.9 ; Make side cut

N008 G00 X1.1 Z-3.8 ; Leave part surface

N008 G00 Z0 ; Rapid move for retracting in Z-axis

N009 M05 X0 ; Spindle off, rapid move to (0,0)

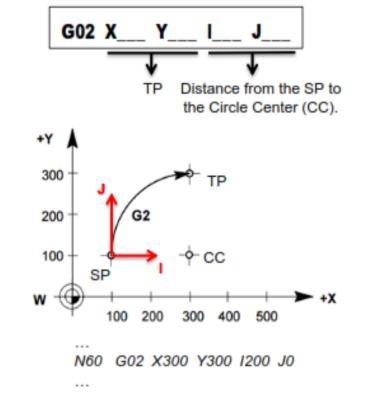
N010 M30 ; End program

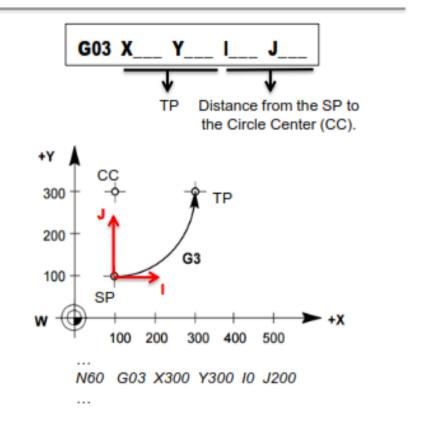
# CARTESIAN COORDINATES WITH ARC CENTER

#### Preparatory functions or G-codes

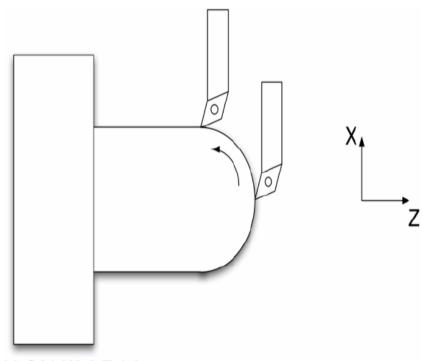
Clockwise circular interpolation (G02) Counterclockwise circular interpolation (G03)

- It is a working circular movement at the programmed F value.
- It can be programmed as G02 or G2 / G03 or G3.





### Circular Interpolation

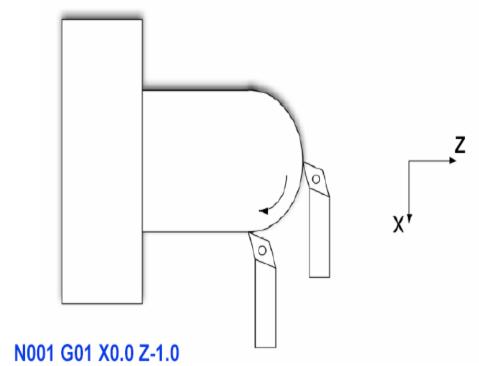


N001 G01 X0.0 Z-1.0

N002 G02 X1.0 Z-2.0 I0.0 K-2.0 F5.0 ; cut CW arc

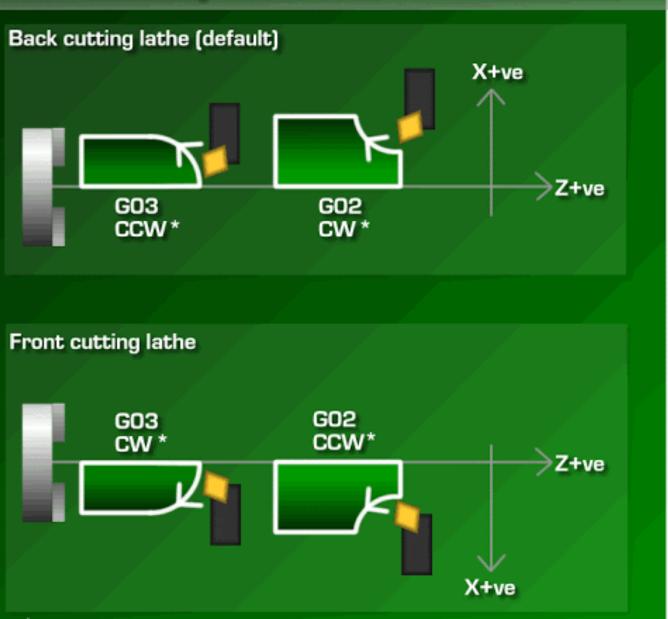
X,Z are end coordinates; I,K are arc center coordinates

CW/CCW Defined by -Y axis NOT STANDARD!



N002 G02 X1.0 Z-2.0 I0.0 K-2.0 F5.0 ; cut CW arc X,Z are end coordinates; I,K are arc center coordinates CW/CCW Defined by -Y axis

#### CNC Turning - Clockwise or Counter Clockwise?



\* CW - Clockwise direction as viewed from top of machine CCW - Counter clockwise as viewed from top of machine

# CARTESIAN COORDINATES WITH ARC RADIUS

#### Preparatory functions or G-codes

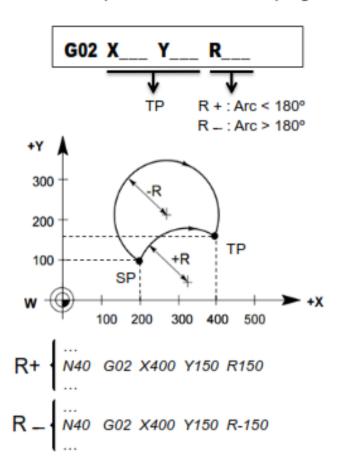
#### Clockwise circular interpolation (G02)

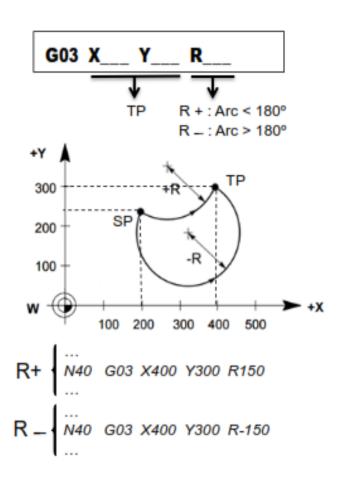


Counterclockwise circular interpolation (G03)



A complete circle cannot be programmed.





#### Preparatory functions or G-codes

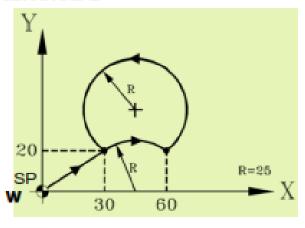
Clockwise circular interpolation (G02)



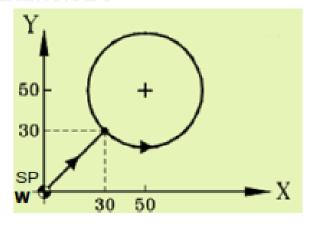
Counterclockwise circular interpolation (G03) 🤇



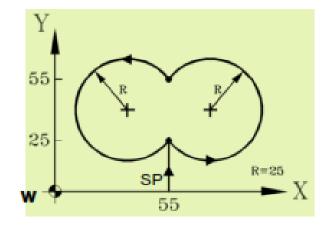
#### **EXERCISE 2**



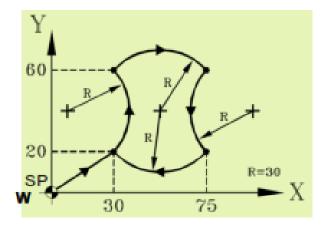
#### **EXERCISE 3**



#### **EXERCISE 4**



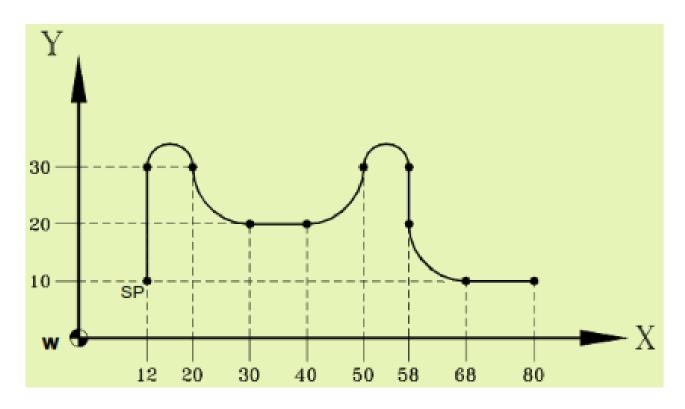
#### **EXERCISE 5**



#### Preparatory functions or G-codes

Clockwise circular interpolation (G02) Counterclockwise circular interpolation (G03)

#### **EXERCISE 6**



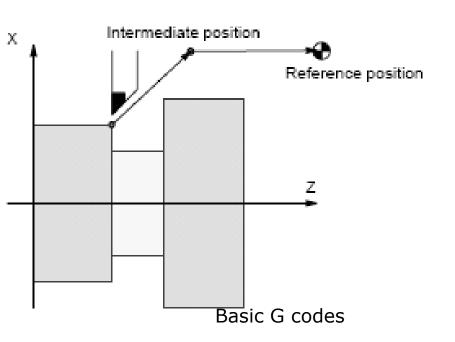
# G28 Reference Position Return

- This code is used to move the turret towards home position for tool indexing with rapid traverse ( No need to cancel offsets, while doing so )

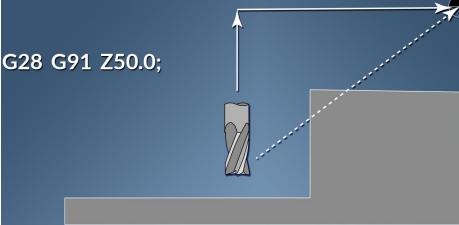
Format is as follows

G28 IP \_\_\_\_

IP is intermediate position



# G28 Reference Return



G28 G91 Z X Y;

G28 - Reference Return

**G91** - Incremental Mode

Z - Distance in Z before return

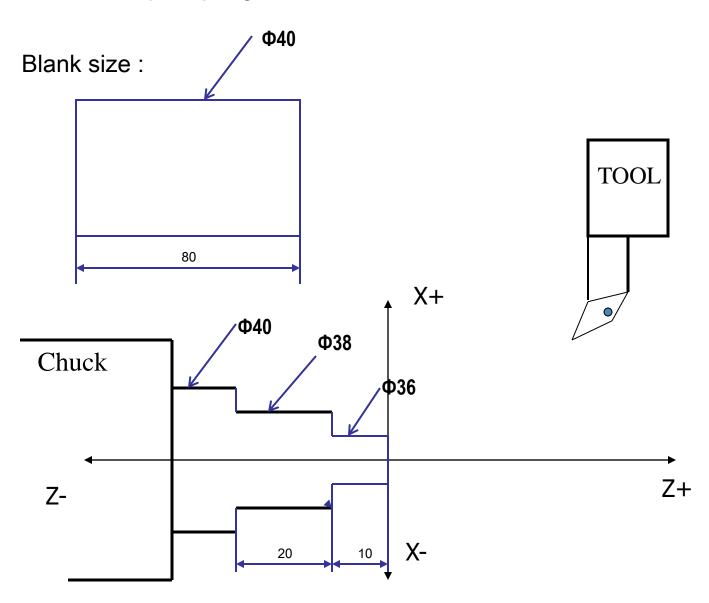
X - Distance in X before return

Y - Distance in Y before return

By stating a distance in an axis before returning to the home position, we can avoid obstacles in the machine

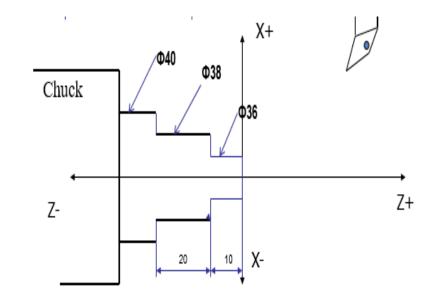
Tutor.com

#### Basic part program

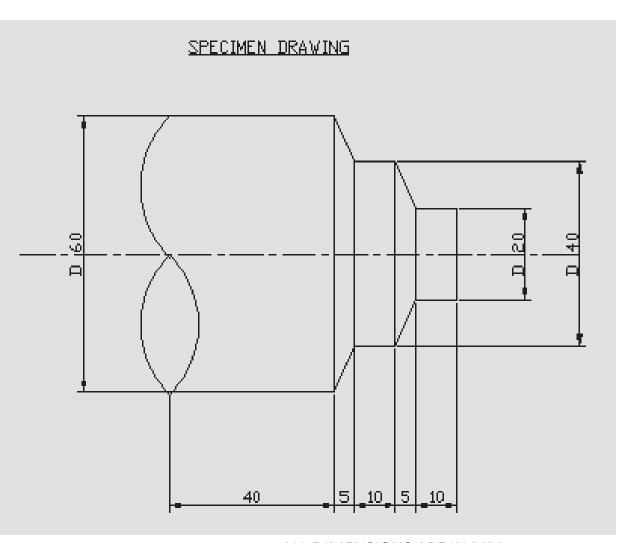


# Program - G01 and G02

- O0001;
- N10 G21 G99;
- N20 G28 UO W0;
- N30 TO1O1;
- N40 S1250 M03;
- N50 G00 X41.0;
- N60 G00 Z0.0;
- N70 G01 X-1.OF0.3;
- N80 G00 Z2.0;
- N90 G00 X41.0;
- N100 G00 Z0.0;
- N110 G01 X38.0 F0.3;
- N120 G01 Z-30.0 F0.3;
- N130 G01 X41.0;
- N140 G00 Z0.0;
- N150 G01 X36.0 F0.3;
- N160 G01 Z-10.0 F0.3;
- N170 G01 X41.0;
- N180 G00 Z0.0;
- N190 G28 U0 W0;
- N200 M05;
- N210 M30;



#### **CNCEZ TURNING - I**



ALL DIMENSIONS ARE IN MM

#### **Program:**

:%

: 1001

N05 G90 M06 T01 G21

N10 M03 S1500

N15 G00 X0 Z0

N20 G01 X20 Z0 F35

N25 G01 X20 Z-10

N30 G01 X40 Z-15

N35 G01 X40 Z-25

N40 G01 X60 Z-30

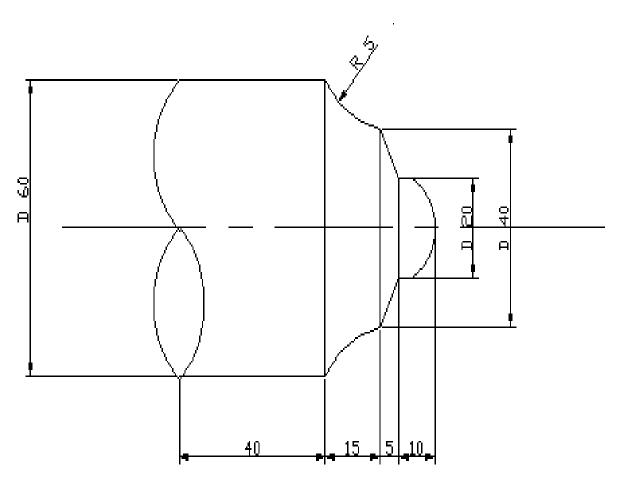
N45 G01 X60 Z-70

N50 G00 X85 Z10

N55 M05 M30

#### **CNCEZ TURNING - II**

#### SPECIMEN DRAWING



#### **Program:**

:%

: 1002

N05 G90 M06 T01 G21

N10 M03 S1500

N15 G00 X0 Z0

N20 G03 X20 Z-5 R10 F40

N25 G01 X20 Z-10

N30 G01 X40 Z-15

N35 G02 X60 Z-25 R 15

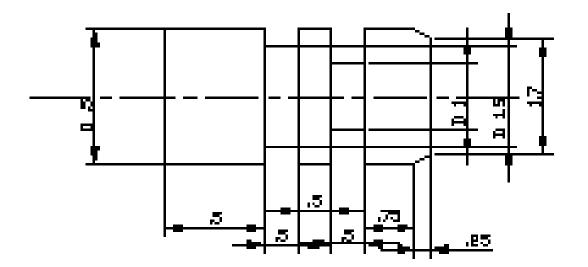
N40 G01 X60 Z-70

N45 G00 X80 Z10

N50 M05 M30

#### **CNCEZ TURNING - III**

#### specimen drawing



All Dimensions Are in Inches

#### Program:

:%

: 1003

N05 G90 G20

N10 M03 S1500

N15 M06 T01

N20 G00 X0 Z0

N25 G01 X1.7 Z0 F40

N30 X2 Z-0.25

N35 X2 Z-2.5

N40 X2.5 Z10

N45 M06 T02

N50 G00 X2 Z-1

N55 G01 X1 Z-1 F40

N60 G01 X1 Z-1.5

N65 G01 X2 Z-1.5

N70 G01 X2 Z-2

N75 G01 X1.7 Z-2

N80 G01 X1.7 Z-2.5

N85 G01X2 Z-2.5

N90 G00 X3 Z1

N95 M05

N100 M30

# **Programming Example**

#### Cylindrical Part

**O0013** 

N0005 G53

N0010 T0303

N0020 G57 G00 X26.00 Z0.0 S500 M04

N0030 G01 X-0.20 F100

N0040 G00 Z2.0

N0050 X50.0 Z50.0

N0060 T0404

N0070 G57 G00 X22.50 Z2.0 S500

N0080 G01 Z-30.0 F100

N0090 G00 X23.0 Z2.0 S500

N0100 G84 X17.5 Z-20.0  $D_0$ =200  $D_2$ =200  $D_3$ =650

N0110 G00 Z2.0

N0120 X50.0 Z50.0

N0130 M30

**O0013** 

**Program identification number** 

O0013

N0005 G53

To cancel any previous working zero point

O0013 N0005 G53 N0010 T0303

N0010 Sequence number T0303 Select tool number 303

```
O0013
N0005 G53
N0010 T0404
N0020 G57 G00 X26.0 Z0.0 S500 M04
G57 To set the working zero point as saved
G00 Rapid movement (no cutting)
X26.0 X location (as a diameter; 13 form zero)
Z0.0 Z location
S500 Spindle speed is 500 rpm
M04 Rotate spindle counterclockwise
      +ve
```

O0013

N0005 G53

N0010 T0404

N0020 G57 G00 X26.00 Z0.0 S500 M04

N0030 G01 X-0.20 F100

**G01** Linear interpolation (cutting)

X-0.20 Move only in x direction until you pass the center by 0.1 mm (facing)

F100 Set feed rate to 100 mm/min.

O0013 N0005 G53

N0010 T0404 N0020 G57 G00 X26.00 Z0.0 S500 M04 N0030 G01 X-0.20 F100 N0040 G00 Z2.0

G00 Move rapidly away from workpiece (no cutting) **Z2.0** the movement is 2 mm away from the face.

```
O0013
```

N0005 G53

N0010 T0404 N0020 G57 G00 X26.00 Z0.0 S500 M04 N0030 G01 X-0.20 F100 N0040 G00 Z2.0 N0050 X50.0 Z50.0

Go to a safe location away from the workpiece [x = 50 (25 from zero), z = 50] to change the tool.

```
O0013
```

```
N0005 G53
N0010 T0404
N0020 G57 G00 X26.00 Z0.0 S500 M04
N0030 G01 X-0.20 F100
N0040 G00 Z2.0
N0050 X50.0 Z50.0
N0060 T0404
```

T0404 Select tool number 404

```
O0013
N0005 G53
N0010 T0404
N0020 G57 G00 X26.00 Z0.0 S500 M04
N0030 G01 X-0.20 F100
N0040 G00 Z2.0
N0050 X50.0 Z50.0
N0060 T0404
N0070 G57 G00 X22.50 Z2.0 S500
G57 PS0
G00 Rapid movement (no cutting)
X22.50 X location (as a diameter; 11.25 form zero)
Z2.0 Z location
S500 Spindle speed is 500 rpm
```

**O0013** 

N0005 G53

N0010 T0404

N0020 G57 G00 X26.00 Z0.0 S500 M04

N0030 G01 X-0.20 F100

N0040 G00 Z2.0

N0050 X50.0 Z50.0

N0060 T0404

N0070 G57 G00 X25.00 Z2.0 S500 M04

N0080 G01 Z-30.0 F100

**G01** Linear interpolation (cutting)

**Z-30 Move only in z direction (external turning)** 

F100 Set feed rate to 100 mm/min.

```
O0013
```

N0005 G53

N0010 T0404

N0020 G57 G00 X26.00 Z0.0 S500 M04

N0030 G01 X-0.20 F100

N0040 G00 Z2.0

N0050 X50.0 Z50.0

N0060 T0404

N0070 G57 G00 X25.00 Z2.0 S500 M04

N0080 G01 X22.5 Z-70.0 F100

N0090 G00 X23.0 Z2.0 S500

G00 Move rapidly away from workpiece (no cutting) to location x = 23.0 (11.50 from zero) and z = 2.0.

```
O0013
```

```
N0005 G53
N0010 T0404
N0020 G57 G00 X26.00 Z0.0 S500 M04
N0030 G01 X-0.20 F100
N0040 G00 Z2.0
N0050 X50.0 Z50.0
N0060 T0404
N0070 G57 G00 X25.00 Z2.0 S500 M04
N0080 G01 X22.5 Z-70.0 F100
N0090 G00 X26.0 Z2.0 S500
N0100 G84 X17.5 Z-20.0 D0=200 D2=200 D3=650
```

G84 Turning cycle for machining the step
X17.5 final diameter
Z-20 length of step is 20 mm

D0=200 Finish allowance in X direction (0.2 mm) D2=200

Finish allowance in Z direction (0.2 mm)

D3=650 Depth of cut in each pass (0.65 mm)

```
O0013
N0005 G53
N0010 T0404
N0020 G57 G00 X26.00 Z0.0 S500 M04
N0030 G01 X-0.20 F100
N0040 G00 Z2.0
N0050 X50.0 Z50.0
N0060 T0404
N0070 G57 G00 X25.00 Z2.0 S500 M04
N0080 G01 X22.5 Z-70.0 F100
N0090 G00 X26.0 Z2.0 S500
N0100 G84 X17.5 Z-20.0 D_0=200 D_2=200 D_3=650
N0110 G00 Z2.0
```

G00 Move rapidly away from workpiece (no cutting) **Z2.0** the movement is 2 mm away from the face.

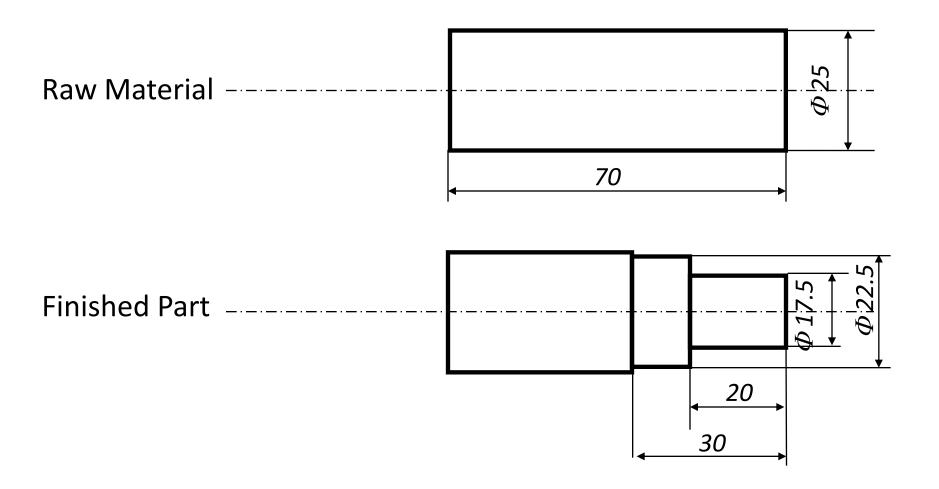
```
O0013
N0005 G53
N0010 T0404
N0020 G57 G00 X26.00 Z0.0 S500 M04
N0030 G01 X-0.20 F100
N0040 G00 Z2.0
N0050 X50.0 Z50.0
N0060 T0404
N0070 G57 G00 X25.00 Z2.0 S500 M04
N0080 G01 X22.5 Z-70.0 F100
N0090 G00 X26.0 Z2.0 S500
N0100 G84 X17.5 Z-20.0 D_0=200 D_2=200 D_3=650
N0110 G00 Z2.0
N0120 X50.0 Z50.0
```

X50.0 Z50.0 Move to the tool changing location

```
O0013
N0005 G53
N0010 T0404
N0020 G57 G00 X26.00 Z0.0 S500 M04
N0030 G01 X-0.20 F100
N0040 G00 Z2.0
N0050 X50.0 Z50.0
N0060 T0404
N0070 G57 G00 X25.00 Z2.0 S500 M04
N0080 G01 X22.5 Z-70.0 F100
N0090 G00 X26.0 Z2.0 S500
N0100 G84 X17.5 Z-20.0 D_0=200 D_2=200 D_3=650
N0110 G00 Z2.0
N0120 X50.0 Z50.0 T00
N0130 M05 M30
```

M30 Program End

# Programming Example Cylindrical Part



# Discussion



Please refer http://www.helmancnc.com/