# **Computer Aided Manufacturing**





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# **Cleansing through Breathing**



# Unit II DRIVES & ND CONTROL

Spindle and feed drives - Sensors - Position, Encoders, Proximity, Limit switch -Interfacing system -Microcontroller and PLC based -Introduction to Graphical User interface -Communication protocol -RS232, RS 485, USB, Ethernet -PLC -Ladder diagram -Peripherals -Timer, Counter, Encoder interface, Human Machine Interface

# Prerequisites Knowledge

• Measuring devices

# **Recap and review of previous class**



# Evocation





# General Objective (GO)

 Students will be able to understand the spindle and axis drives in Computer Numeric Control (CNC) machines and evaluate their suitability to achieve precision of machining.

# **Specific Objectives**

## Students will be able to

- Recognize the type of drives used in CNC machines (R/F) (T)
- Explain the working concept of the drives used for spindles and feed in CNC machines. (U / C)
  (E)
- Attribute the requirements for spindle and axis drives used in CNC machines for smooth operation. (An / C) (E)
- Check the two drives suitable for axis movement in CNC machines based on precision machining of automobile steel part to fit and function at high speed rotation. (E / P) (E)

# What is sensing?

**Sensing** is converting a quantity that you want to measure into a useable signal (usually electronic).

**Perception** is the interpretation or understanding of these signals.

## Example:

**Sensing:** Sound waves -> vibrating eardrums -> signals to brain **Perception:** Understanding that I am talking to you about sensors.

#### **Feedback Devices**

Two types of feed back devices normally used are:

1. Positional Feed Back Devices

1.1 Linear Transducers - a device mounted on the machine table to measure the actual displacement of the slide in such a way that backlash of screws, motors etc. would not cause any error in the feed back data.



https://www.indiamart.com/proddetail/cnc-linear-encoder-12573739991.html

#### **Feedback Devices**

1.2 Rotary Encoders: a device to measure the angular displacement. It cannot measure linear displacement directly so that error may occur due to the backlash of screw and motor etc.



# The closed loop feedback control system



# The absolute encoder disc for rotary position measurement.





#### Operation of a digital rotary encoder for position measurement



# The encoder disc mounted on the lead screw



# Principle of optical grating for position measurement in linear scales



# The linear scale fixed to the machine tool structure



#### **Analysis of Positioning NC Systems**

Three measures of precision:

- 1. Control resolution distance separating two adjacent addressable points in the axis movement
- Accuracy maximum possible error that can occur between the desired target point and the actual position taken by the system
- 3. Repeatability defined as  $\pm 3\sigma$  of the mechanical error distribution associated with the axis

#### Control Resolution, Accuracy, and Repeatability



#### **Velocity Feedback Device**

- The actual speed of the motor can be measured in terms of voltage generated from a tachometer mounted at the end of the motor shaft.
- The voltage generated by the DC tachometer is compared with the command voltage corresponding to the desired speed.
- The difference of the voltages is used to actuate the motor to eliminate the error.



# **Proximity Measurement**

- Measurement can be caused by ...
  - a known obstacle.
  - cross-talk.
  - an unexpected obstacle (people, furniture, ...).
  - missing all obstacles (total reflection, glass, ...).
- Noise is due to uncertainty ...
  - in measuring distance to known obstacle.
  - in position of known obstacles.
  - in position of additional obstacles.
  - whether obstacle is missed.



### Introduction

Inductive Proximity switches are solid state sensing devices which require no physical contact to actuate them.

#### **Main Advantages**

- Exceptionally long life & high switching speeds.
- Non contact, zero operation force.
- Wear & maintenance free operation.
- Bounce free signals.
- Reliable switching under extreme conditions.
- Fully waterproof.



#### **Overview of Range**

- Cylindrical proximity switches from M8 to M30 diameter with AC or DC operation, flush or non-flush mounting in brass or stainless steel housing.
- Inductive Proximity switches in Flat profile plastic housings. (for applications with constraint on mounting space)
- Inductive Proximity switches in Block housings (similar to limit switches).





- Mounting Flush
- Extremely rigid Stainless Steel Housing.
- Sensing Distance Sn= 1 mm or 1.5 mm
- Hysteresis  $\leq$  0.15 mm.
- Repeat Accuracy ≤ 0.05 mm.



- Operating Voltage 10-30 VDC.
- Connection either through encapsulated cable or plug and socket.
- Switching frequency 2000 Hz.
- Output polarity : PNP / NPN.
- Output function : NO.
- Short circuit and reverse polarity protection.



- Mounting Flush or Non-flush
- Nickel Plated Brass Housing.
- Sensing Distance Sn= 2 mm (flush type) or 4 mm (non-flush type)
- **Extended version** has sensing distance of 4 mm on flush type.
- Hysteresis  $\leq$  0.2 mm (Sn=2 mm) / 0.6 mm (Sn=4 mm).
- Repeat Accuracy ≤ 0.1 mm (Sn= 2 mm).





- Operating Voltage 10-30 VDC.
- Connection either through encapsulated cable or plug and socket.
- Switching frequency 1000 Hz.
- Output polarity : PNP / NPN.
- DC 2 wire versions also available.
- Output function : NO / NO + NC
- Short circuit and reverse polarity protection.





- Mounting Flush or Non-flush
- Nickel Plated Brass Housing
- Sensing Distance Sn= 5 mm (flush type) or 8 mm (non-flush type)
- **Extended version** has sensing distance of 8 mm on flush type
- Hysteresis  $\leq$  0.5 mm (Sn=5 mm) / 0.8 mm (Sn=8 mm)
- Repeat Accuracy ≤ 0.2 mm (Sn= 5 mm)





- Operating Voltage 10-30 VDC, 90-230 VAC
- Connection either through encapsulated cable or plug and socket
- Switching frequency 500 Hz. (DC versions only)
- Output polarity : PNP / NPN
- DC 2 wire versions also available
- Output function : NO / NO + NC
- Short circuit and reverse polarity protection. (DC versions only)





- Mounting Flush or Non-flush
- Nickel Plated Brass Housing.
- Sensing Distance Sn= 10 mm (flush type) or 15 mm (non-flush type)
- Hysteresis  $\leq$  1.0 mm (Sn=10 mm) / 1.5 mm (Sn=15 mm).
- Repeat Accuracy  $\leq 0.5 \text{ mm}$  (Sn= 10 mm).





- Operating Voltage 10-30 VDC, 90-230 VAC
- Connection either through encapsulated cable or plug and socket
- Switching frequency 300 Hz. (DC versions only)
- Output polarity : PNP / NPN
- Output function : NO / NC / NO + NC (only DC version)
- Short circuit and reverse polarity protection. (DC versions only)





## Proximity Switches in Flat Profile Housing

- Mounting through mounting holes
- Plastic Housing.
- Sensing Distance Sn = 5 mm (FG2 type) or 2 mm (FG4 type)
- Hysteresis  $\leq$  0.5 mm (Sn=5 mm) / 0.2 mm (Sn=2 mm)
- Repeat Accuracy ≤ 0.1 mm (Sn= 2 mm)
- Operating Voltage 10-30 VDC





## **Proximity Switches in Block Housing**

- Mounting through mounting holes
- Die cast aluminium Housing
- Sensing Distance Sn= 5 mm (SN01 & N1A type)
- Hysteresis  $\leq$  0.5 mm (Sn=5 mm)
- Repeat Accuracy ≤ 0.2 mm (Sn= 5 mm)





## **Proximity Switches in Block Housing**

- Operating Voltage 10-30 VDC
- Connection either through encapsulated cable or plug and socket
- Switching frequency 500 Hz
- Output polarity : PNP / NPN
- Output function : NO
- Short circuit and reverse polarity protection





### **Connectors for Proximity Switches**

#### Types

- Field wire able types SGF and SBF
- Molded cable connectors without LED with PVC or PUR cable.
- Molded cable connectors with LED and PUR cable suitable for PNP type proximity switches.





## Limit Switches





# Limit Switches

- A limit switch has the same ON/OFF characteristics.
- The limit switch usually has a pressure-sensitive mechanical arm.
- When an object applies pressure on the mechanical arm, the switch circuit is energized.
- An object might have a magnet attached that causes a contact to rise and close when the object passes over the arm.

When the moving object touches and moves the lever, a set of electrical contacts is forced either open or closed.



# <u>Limit Switches</u>

- Limit switches can be either
  - Normally open (NO) or
  - Normally closed (NC) and may have multiple poles.
- A normally open switch has continuity when pressure applied and a contact is made.
- While a normally closed switch opens when pressure is applied.

## Limit Switches



Figure A.2: Normally Open-Normally Closed Limit Switches

## Limit Switches- Types

- A single pole switch allows one circuit to be opened or closed upon switch contact.
- Multiple-pole switch allows multiple circuits to be opened or closed.

# Limit Switches

Limit switches are mechanical devices.

Limit Switches has following drawback:

- They are subject to mechanical failure.
- Their mean time between failures (MTBF) is low compared to non-contact sensors.
- Their speed of operation is relatively low; the switching speed of photoelectric microsensors is up to 3000 times faster

# Limit Switches -Advantages

- Limit switches are mechanical position-sensing devices that offer simplicity, robustness, and repeatability to processes.
- Mechanical limit switches are simplest in which contact is made and a switch is engaged.
- Limit switches are easy to maintain because the operator can hear the operation of the switch and can align it easily to fit the application.

# Limit Switches -Advantages

- They are also robust. They can handle an inrush current
  10 times that of their steady state rating.
- Reliability is another benefit. Published claims for repeat accuracy for standard limit switches vary from within 0.03mm to within 0.001mm over temperature range of 4 to +200F.
- Limit switch dissipate energy spikes and rarely break down under normal mode surges. They will not be affected by electromagnetic interferences (EMI).

# Discussion



## THANK YOU FOR YOUR PATIENCE AND TIME

